



Photovoltaic Systems Engineering

Ali Karimpour

Assistant Professor

Ferdowsi University of Mashhad

Reference for this lecture:

Photovoltaic Systems Engineering Third Edition CRC

Roger Messenger, Jerry Ventre

Lecture 8

2
0
1
2



PV System Loads and Electronics

PV System Loads

System Availability

System Electronic Components

Introduction

Charge Controllers

MPPT circuits

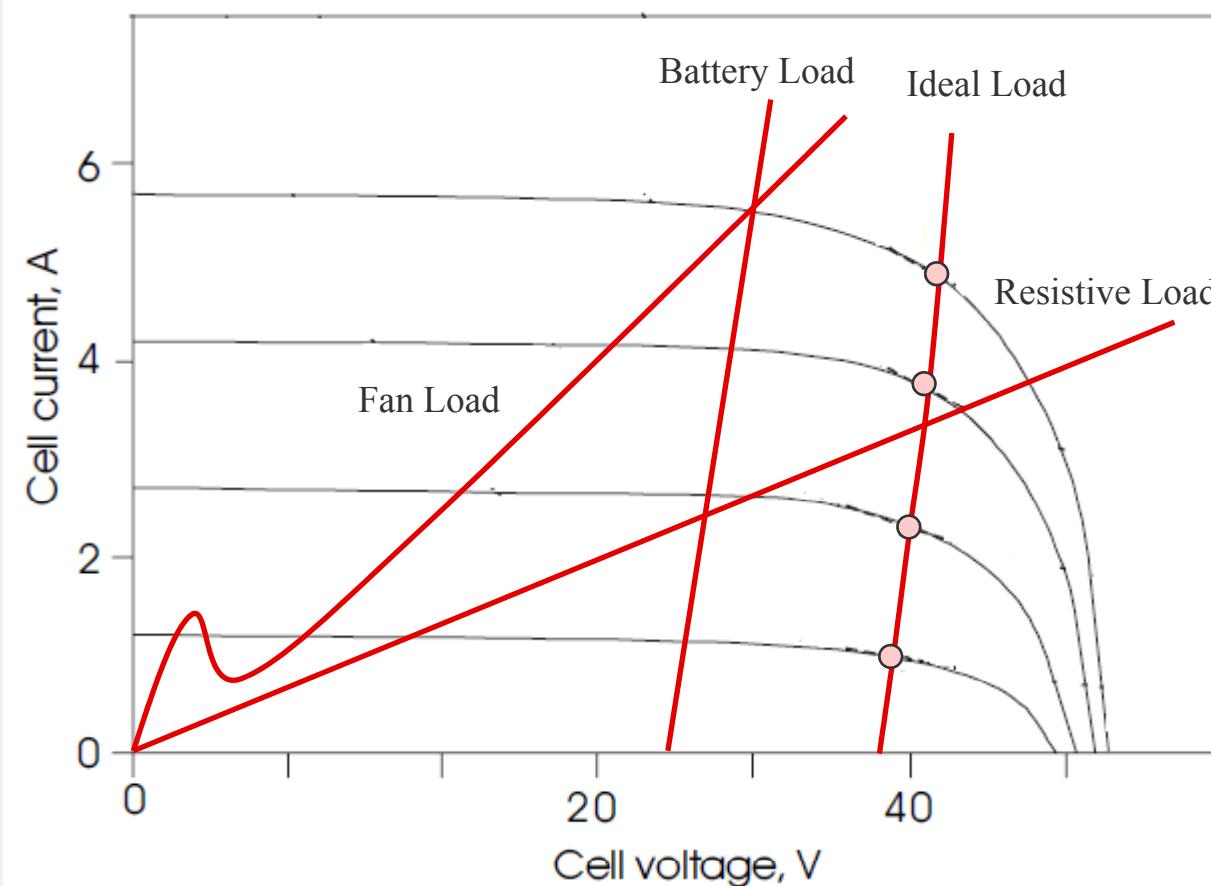
Inverters

2

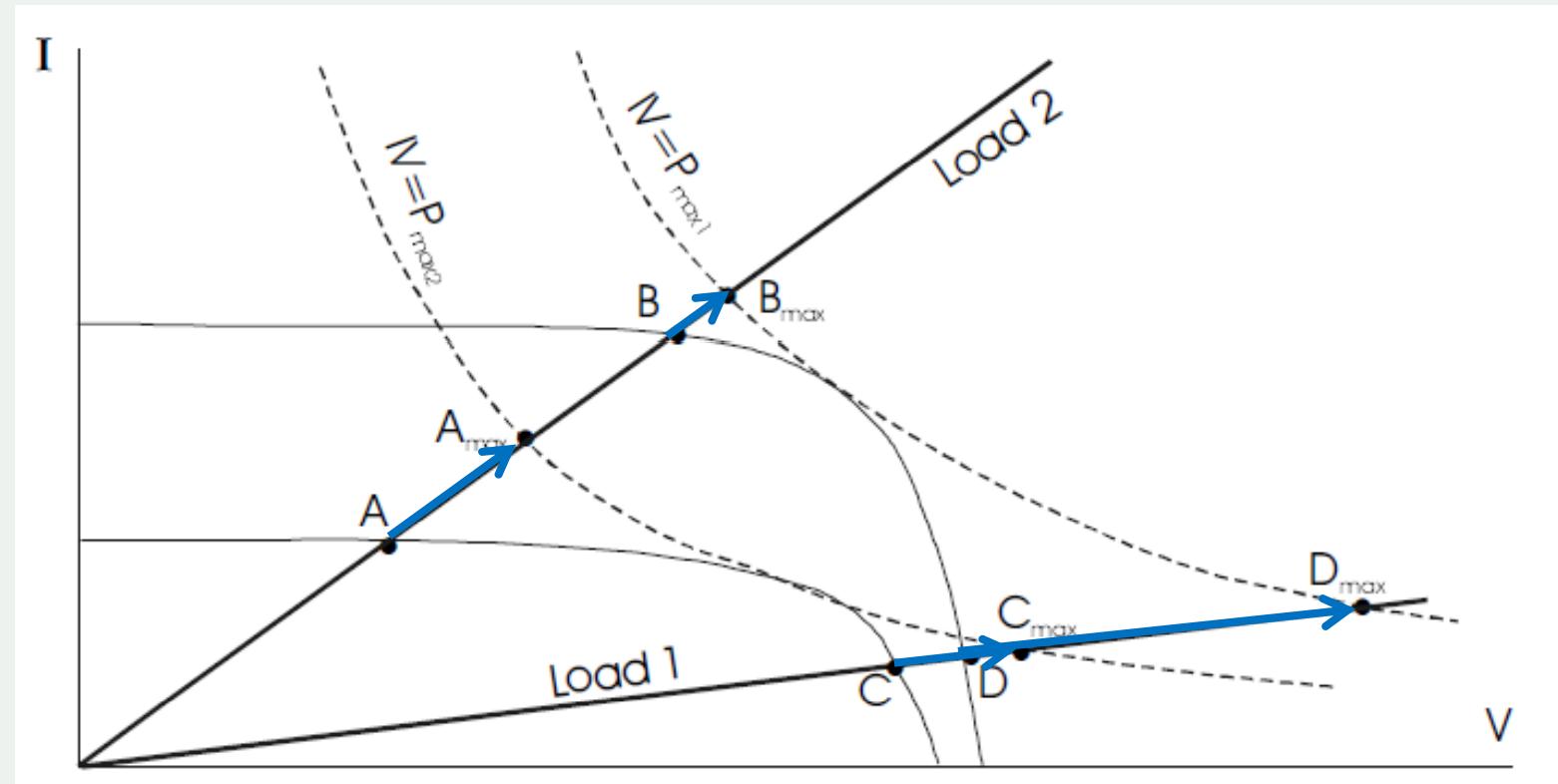


V-I characteristic of a PV

Ideal Load
Resistive Load
Battery Load
Fan Load



MPPT

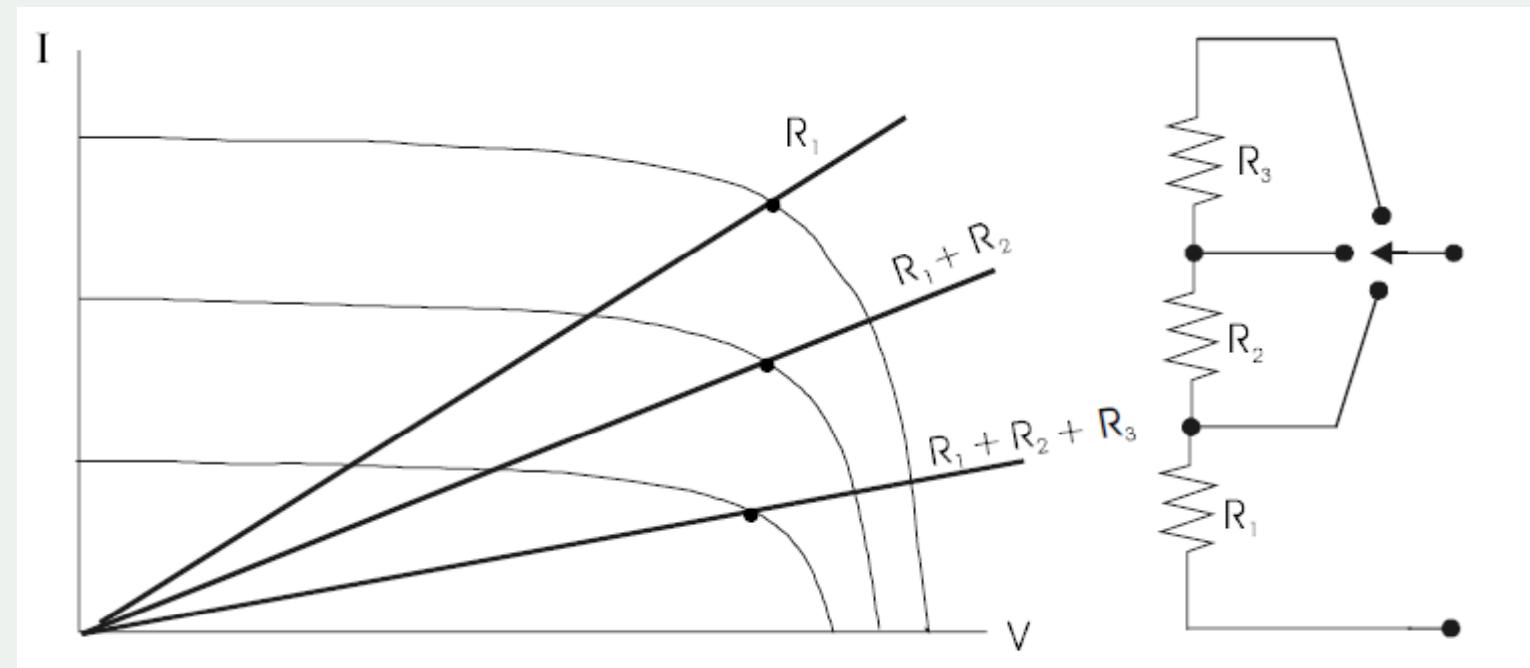
2
0
1
2

But How is it possible?

4



MPPT: Variable resistors

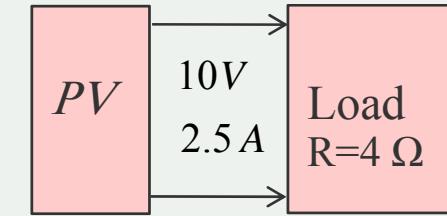
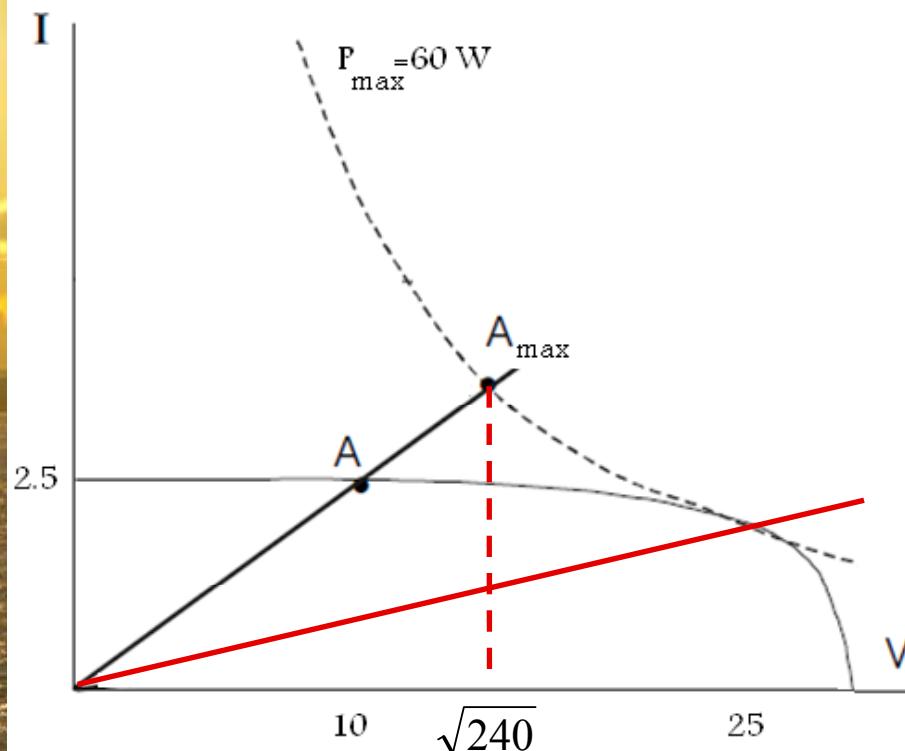


Is it acceptable to pay more initial cost?

Is it acceptable to pay for a MPPT?

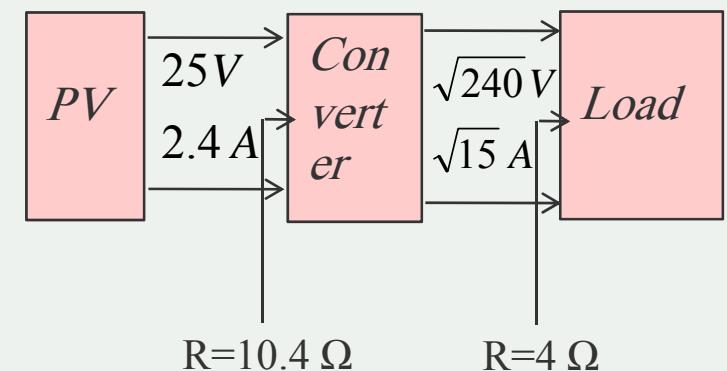
MPPT

2
0
1
2



25W

$25W \xrightarrow{?} 60W$



System Availability

2
0
1
2



Downtime reasons in conventional power systems:

- Sc in the system
- Failure of a generator
- Overload
- Failure in the turbine
-

Downtime reasons in PV systems:

- Loose or corroded connections
- Battery failure
- Controller failure
-

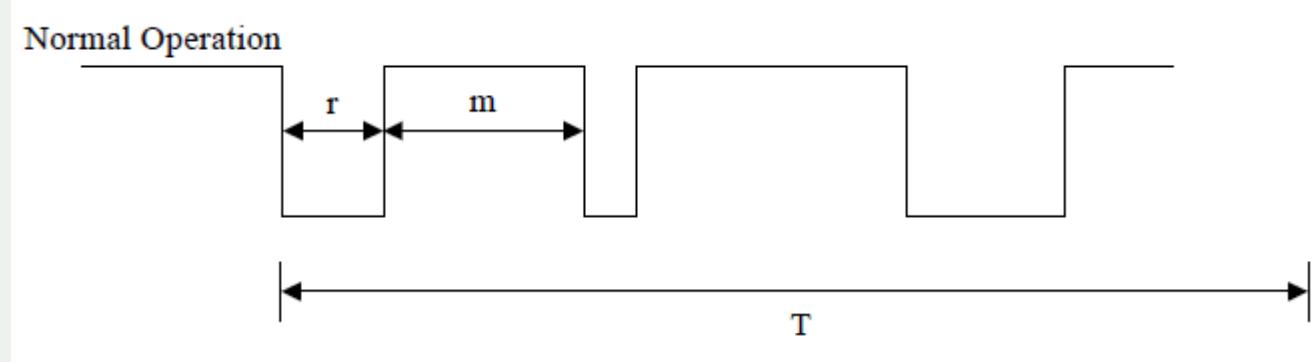
And also unpredictable cloud cover → Enough battery storage.

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System Availability

Availability definition



$$\text{Availability} = \frac{\sum m}{T}$$

Critical loads: 99% availability

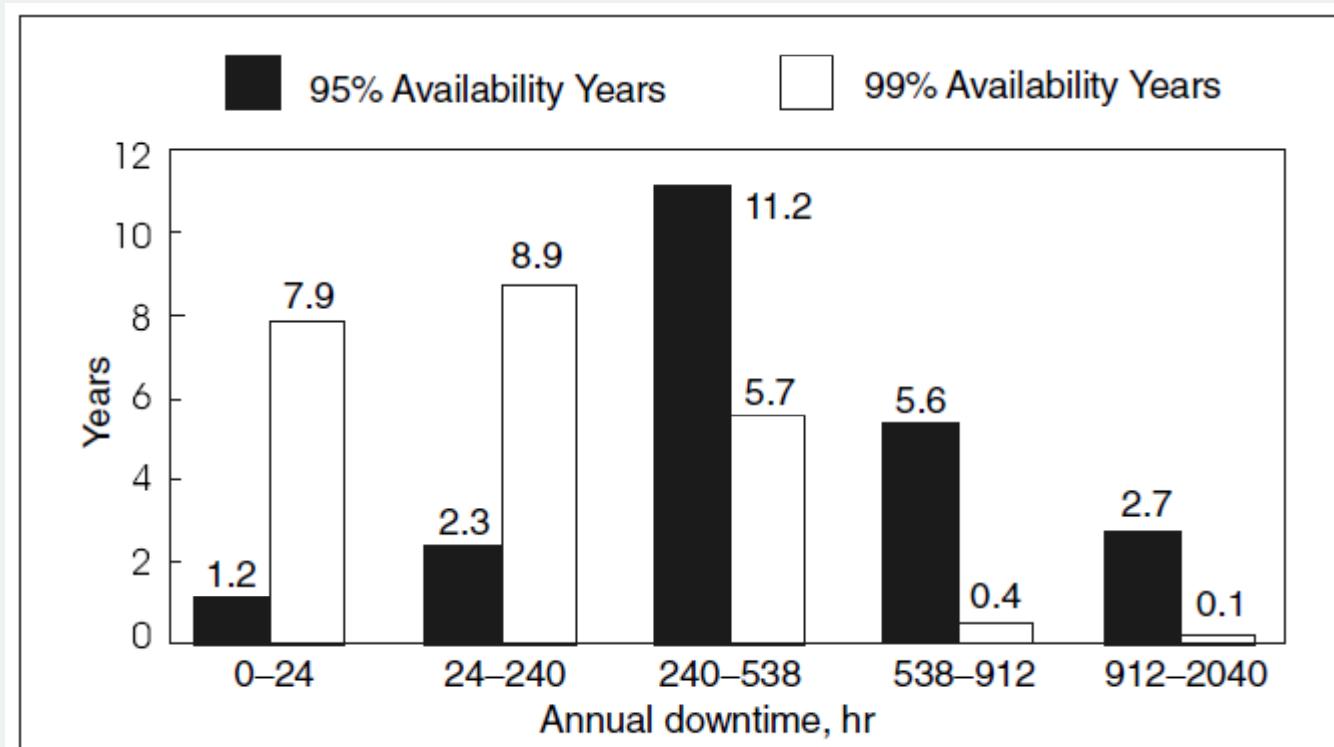
Noncritical loads: 95% availability



System Availability

Critical loads: 99% availability

Noncritical loads: 95% availability

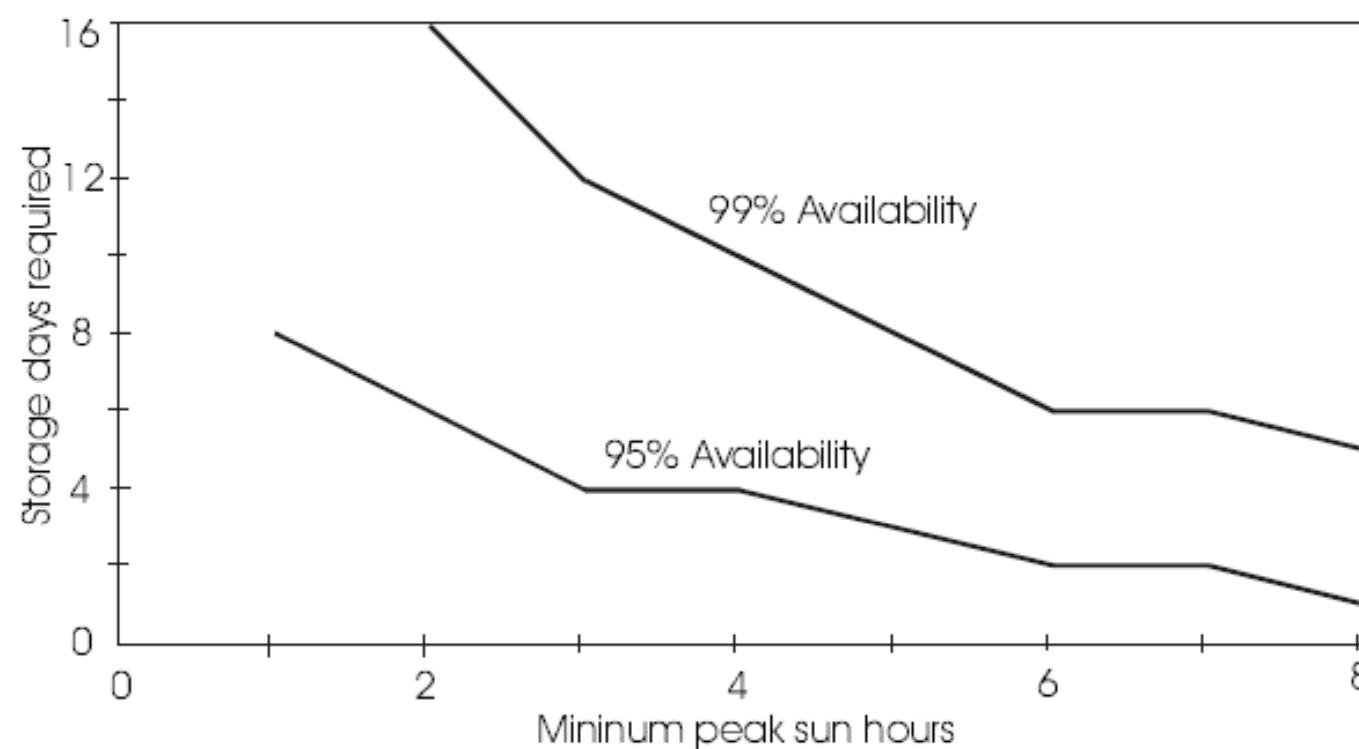


Statistical distribution of annual downtime for critical and noncritical PV systems over a 23-year system lifetime.



System Availability

Storage days required for a system



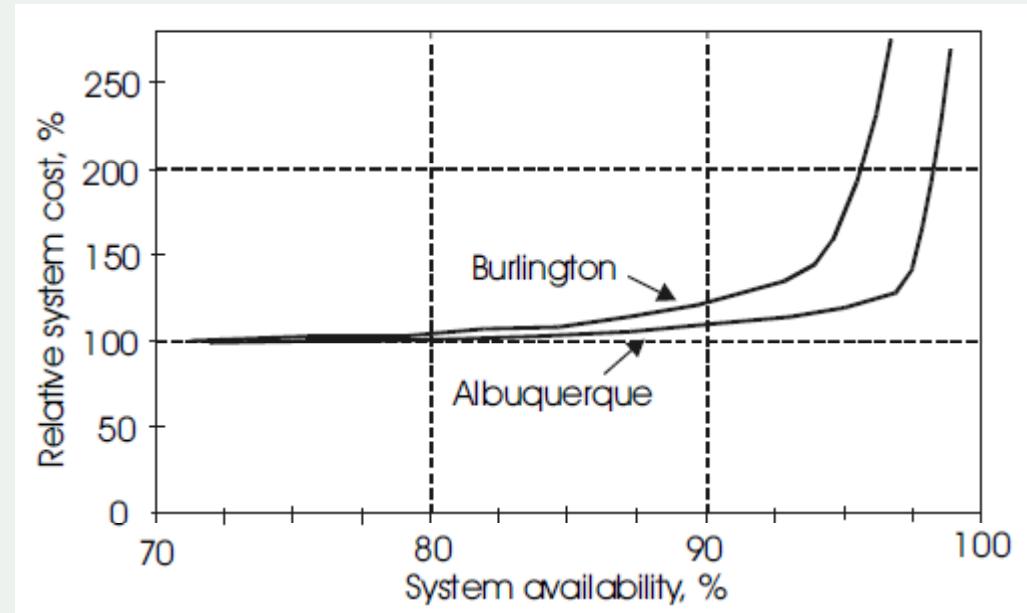
$$D_{crit} = 0.2976T_{min}^2 - 4.7262T_{min} + 24$$

$$D_{non} = 0.1071T_{min}^2 - 1.869T_{min} + 9.4286$$

System Availability

2
0
1
2

Price of system availability



Burlington latitude is around 44°

Albuquerque latitude is around 35°



System Electronic Components

System Electronic Components

Introduction

Charge Controllers

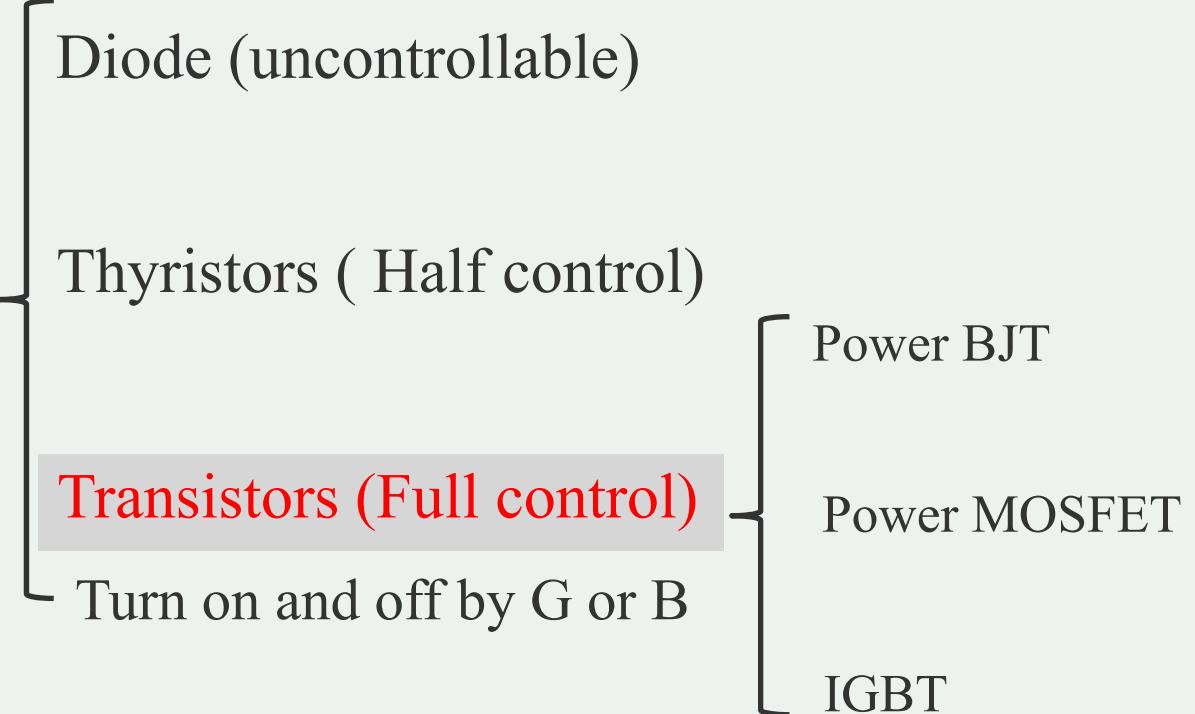
MPPT circuits

Inverters

Introduction

2
0
1
2A photograph of a sunset over a body of water, with the sun low on the horizon and its reflection visible on the water's surface.

Power
semiconductor
switches



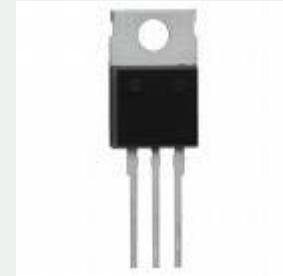
BJT: Bipolar Junction Transistor.

MOSFET: Metal–Oxide Semiconductor Field-Effect Transistor.

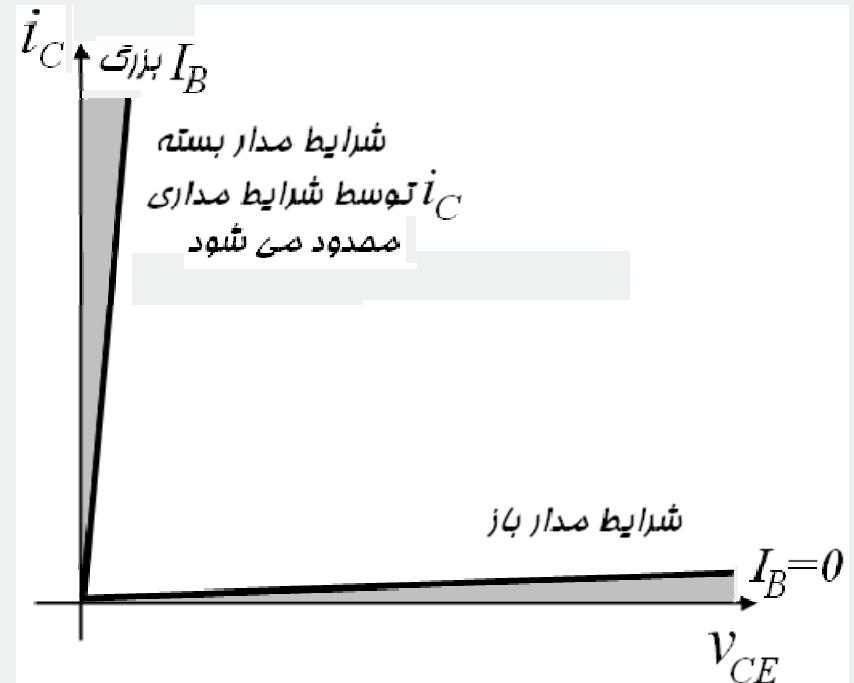
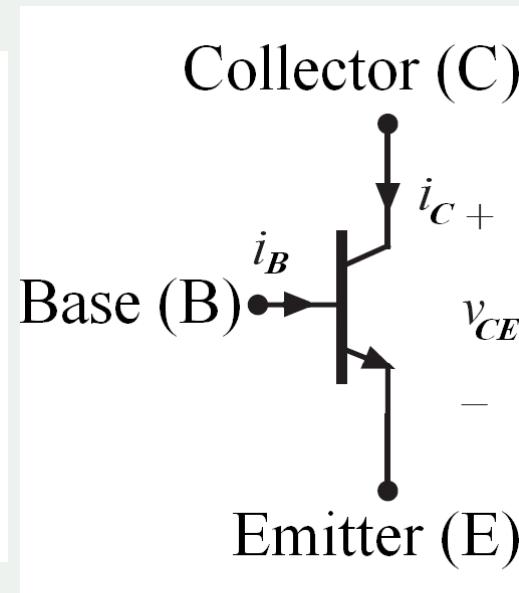
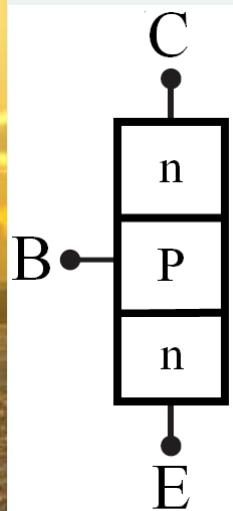
IGBT: Isolated Gate Bipolar Transistor.

Transistors (Power BJT)

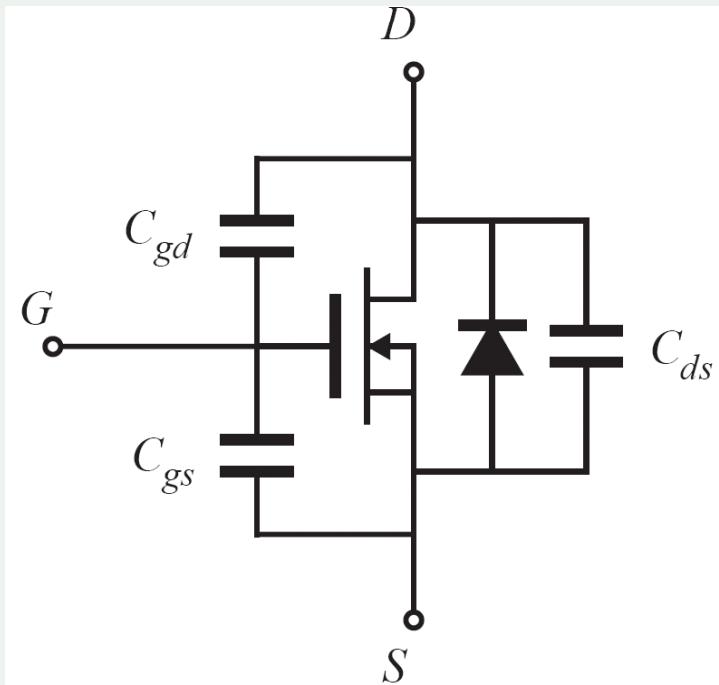
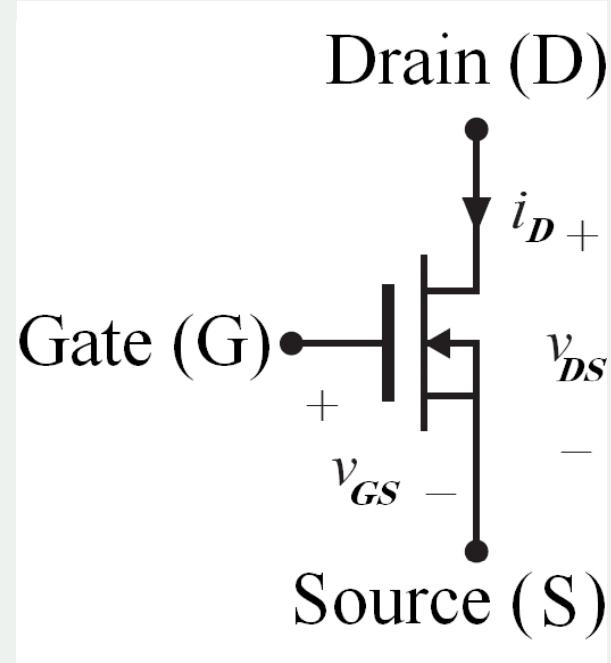
2
0
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2



Transistors (Power BJT)

2
0
1
2

Transistors (Power MOSFET)

2
0
1
2



Transistors (Compare BJT and MOSFET)

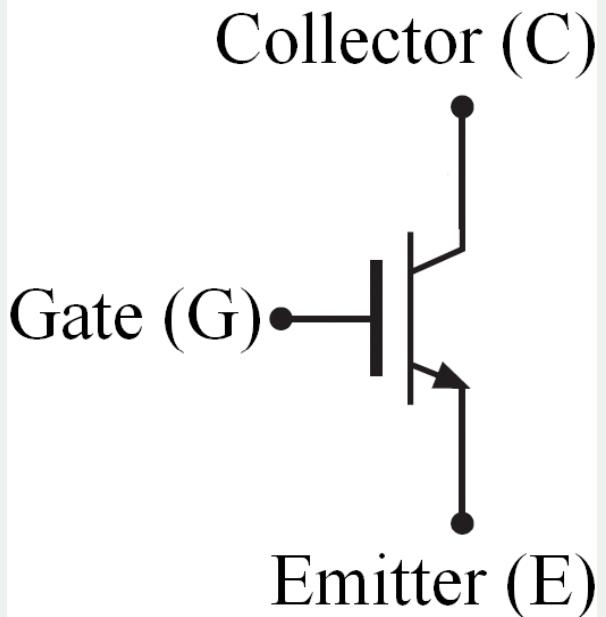


MOSFET	BJT
امپدانس ورودی بالا-کنترل شونده با ولتاژ	امپدانس ورودی کم-کنترل شونده با جریان
فرکانس کلیدزنی بالا	فرکانس کلیدزنی متوسط
افت ولتاژ هدایت مستقیم بیشتر	افت ولتاژ هدایت مستقیم کمتر
نویزپذیری بیشتر	نویزپذیری کمتر
کنترل راحت تر	کنترل مشکل تر
در قدرت های پایین تر موجود است	در قدرت های بالاتر موجود است
ضریب حراطی مثبت	ضریب حراطی منفی

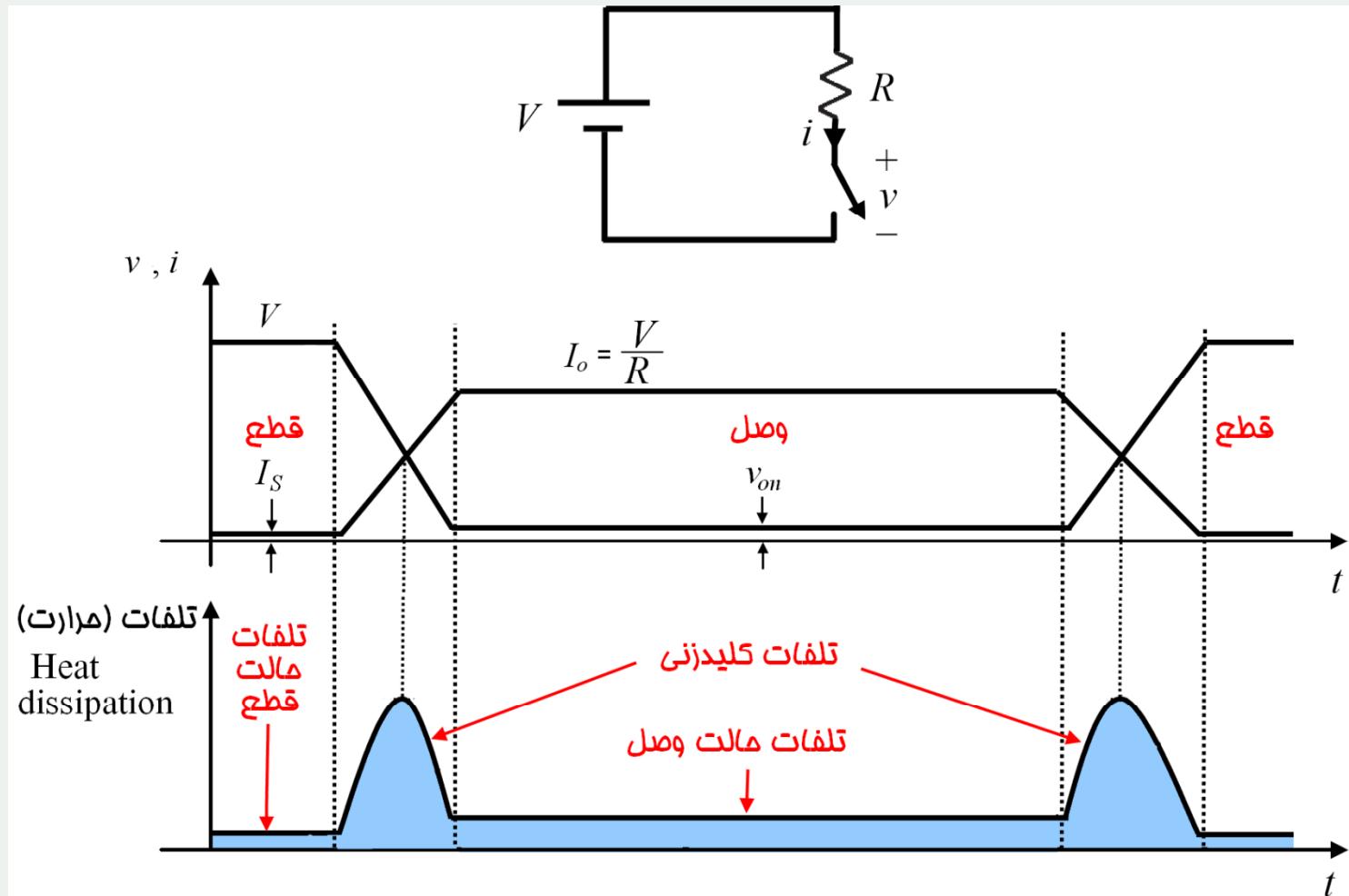


Transistors (IGBT)

- در خروجی دارایی مزایایی BJT یعنی افت ولتاژ مستقیم کوچک (تلفات هدایت کم) y
- در ورودی دارایی مزایایی MOSFET یعنی جریان ناچیز و سادگی مدار گیت y
- ضریب حرارتی مثبت y
- سادگی موازی شدن x
- سرعت کلیدزنی بین BJT و MOSFET y
- جایگزین BJT در قدرت های متوسط و بالا y

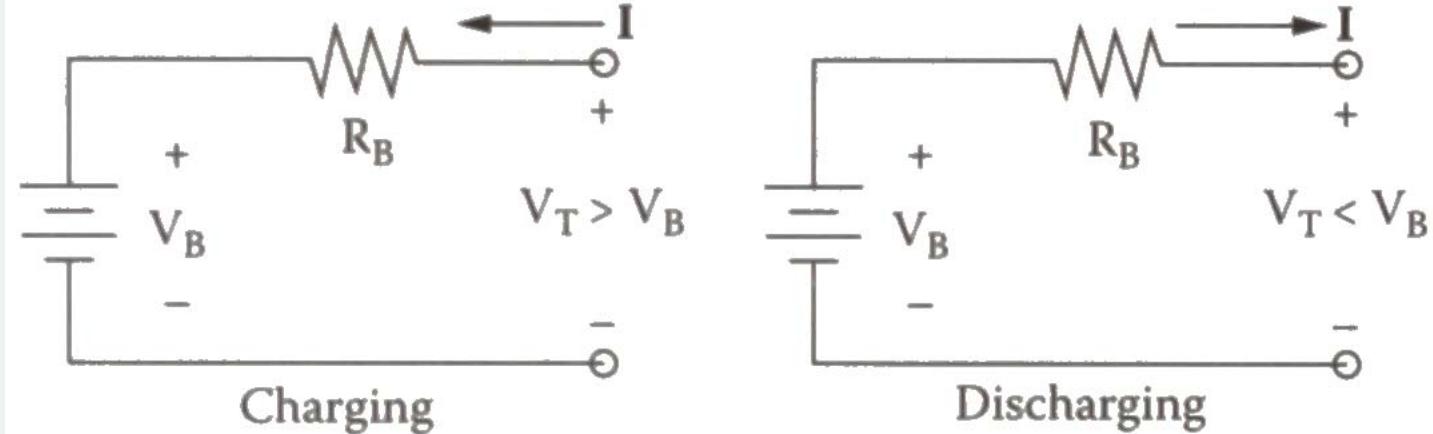


Losses in Transistors

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2



Charge controllers



SOC (state of charge) can be measured by V_B

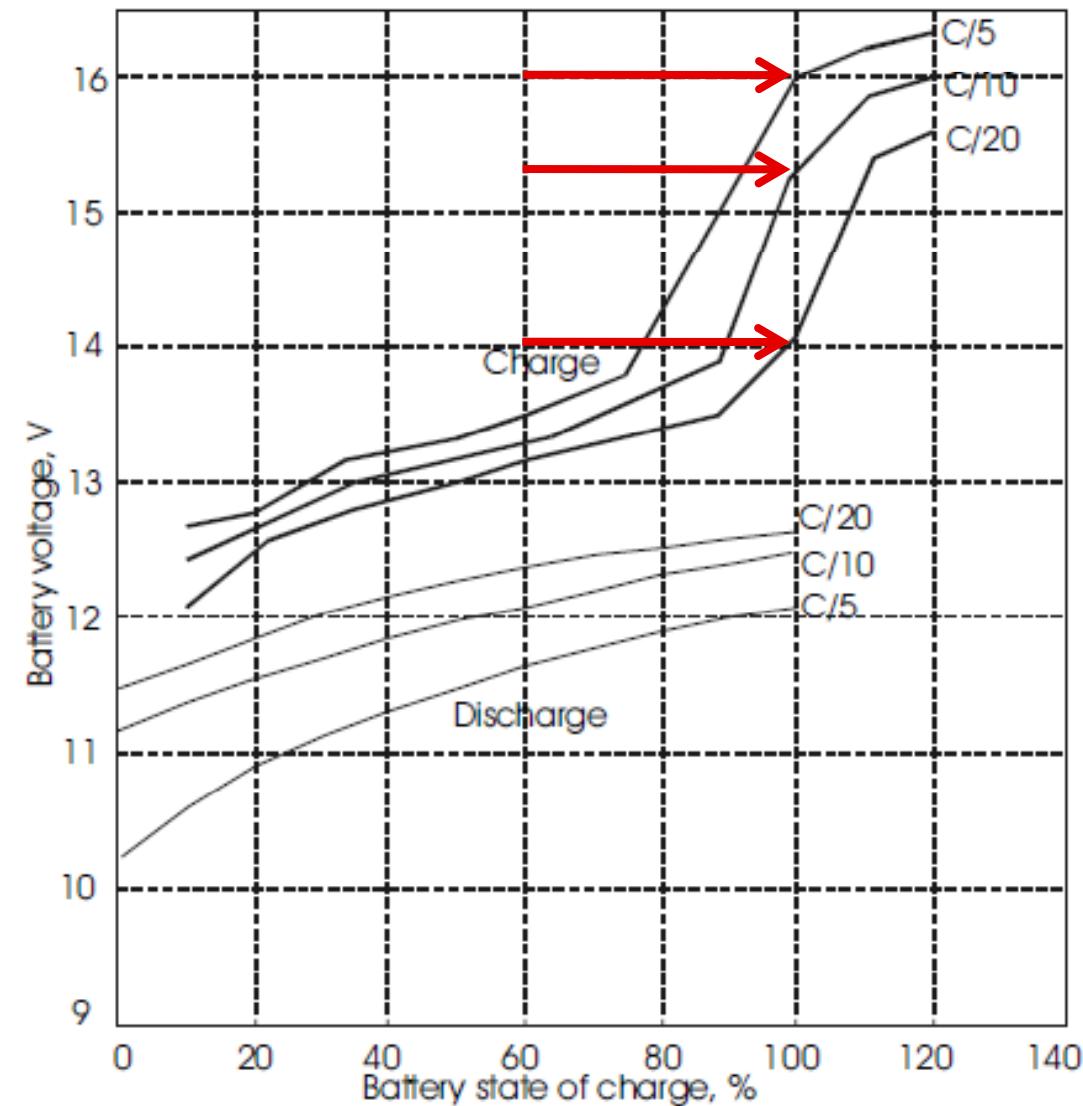
Is V_B available in charging condition?

Can one estimate V_B by knowing R_B ?

Both V_B and R_B are temperature dependent.
 R_B is age dependent too.



Charge Controllers

Let $V=14$ (C/20)

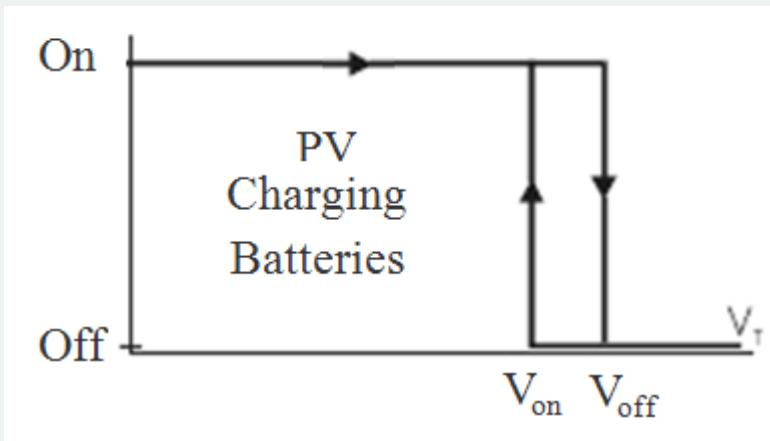
Disconnect
V decreases
Connect
V increases

Charge Controllers

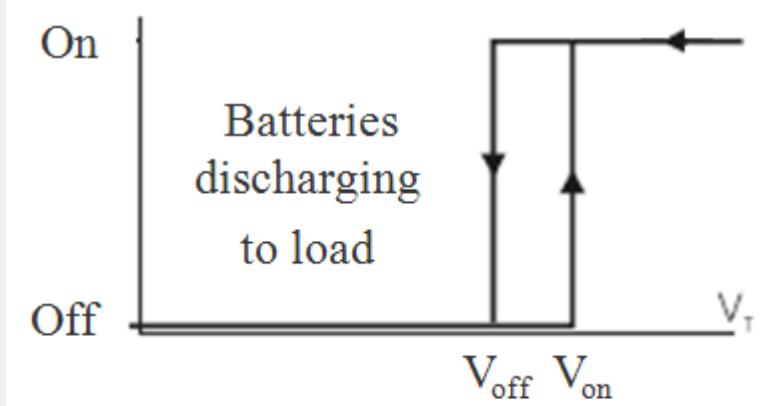
2
0
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2

Hysteresis can help and solve the problem.

In the charging period:



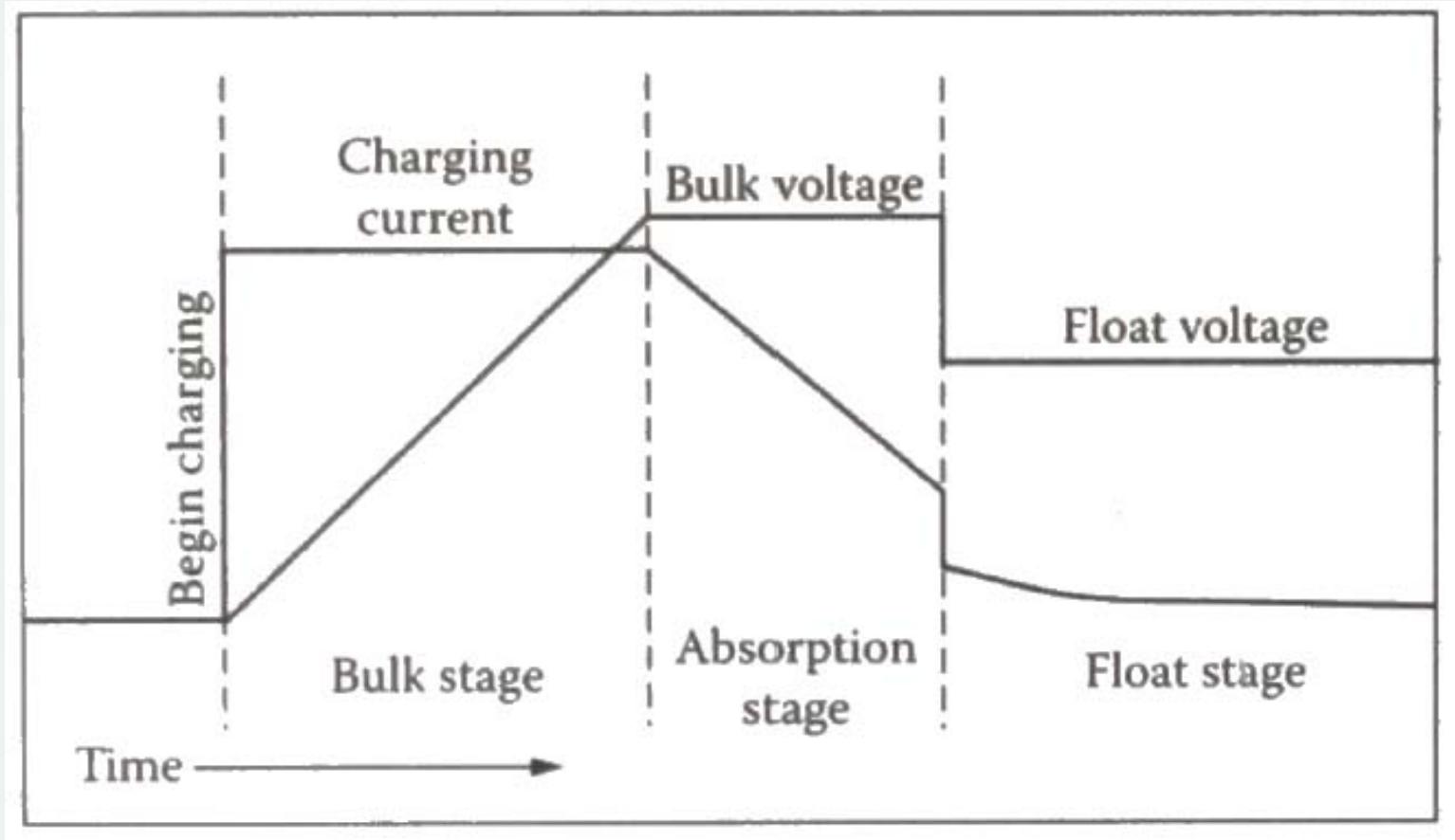
In the discharging period:



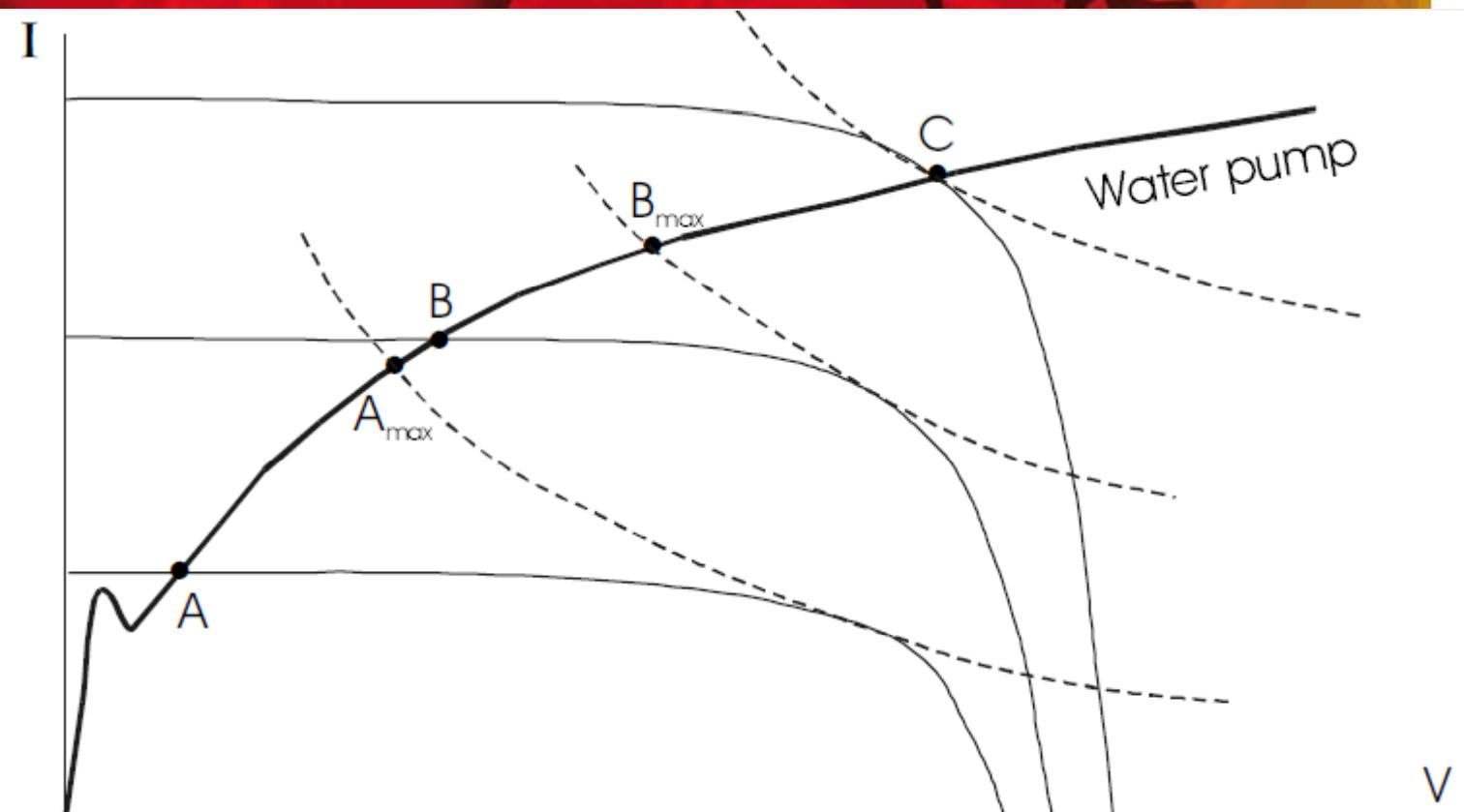
Charge Controllers

2
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1
2

Three stage battery charge control



MPPT circuits

2
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1
2

One must $A \rightarrow A_{max}$ this is possible by an electronic circuit.

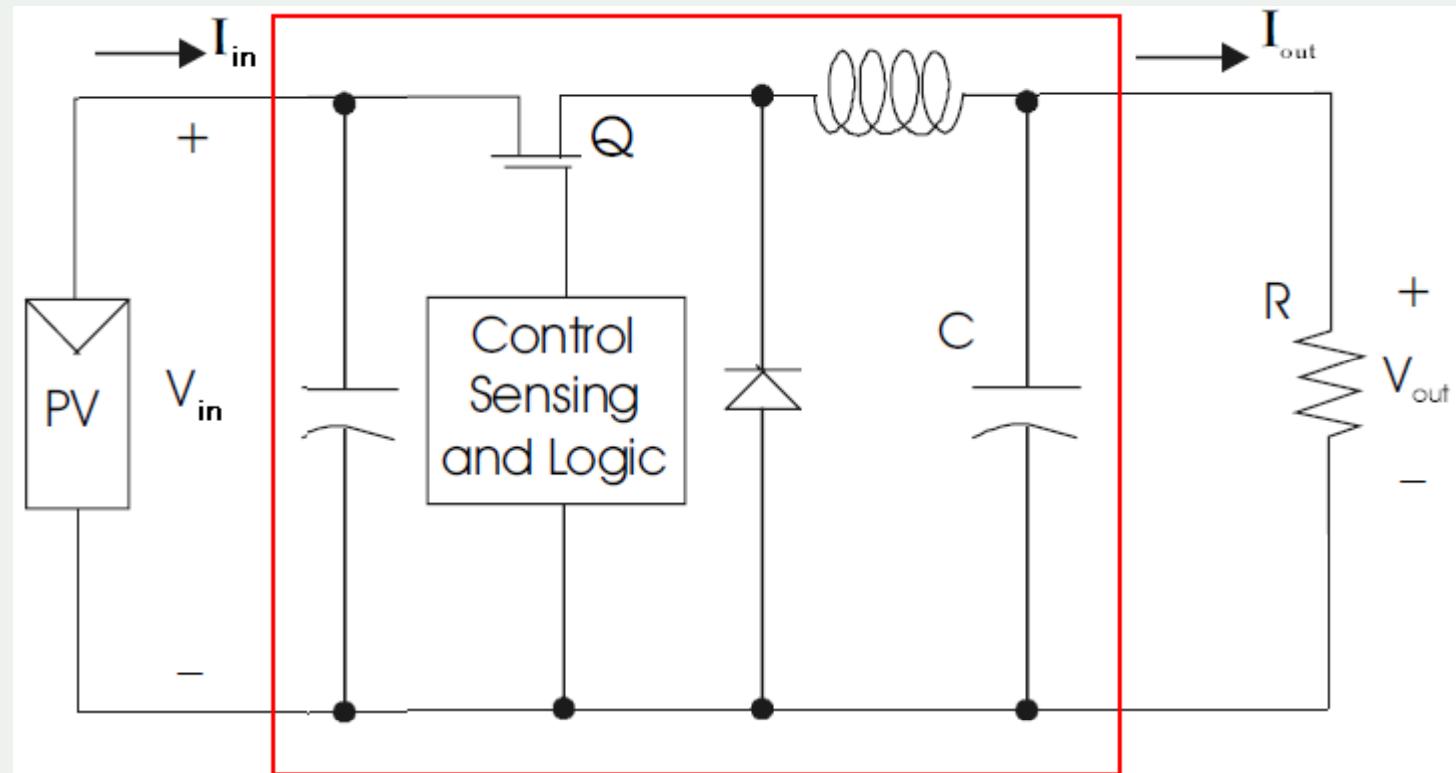
V_p must decrease and I_p must increase.

Use a buck convertor (Linear Current Booster)

MPPT circuits

2
0
1
2

A buck converter (Linear Current Booster)

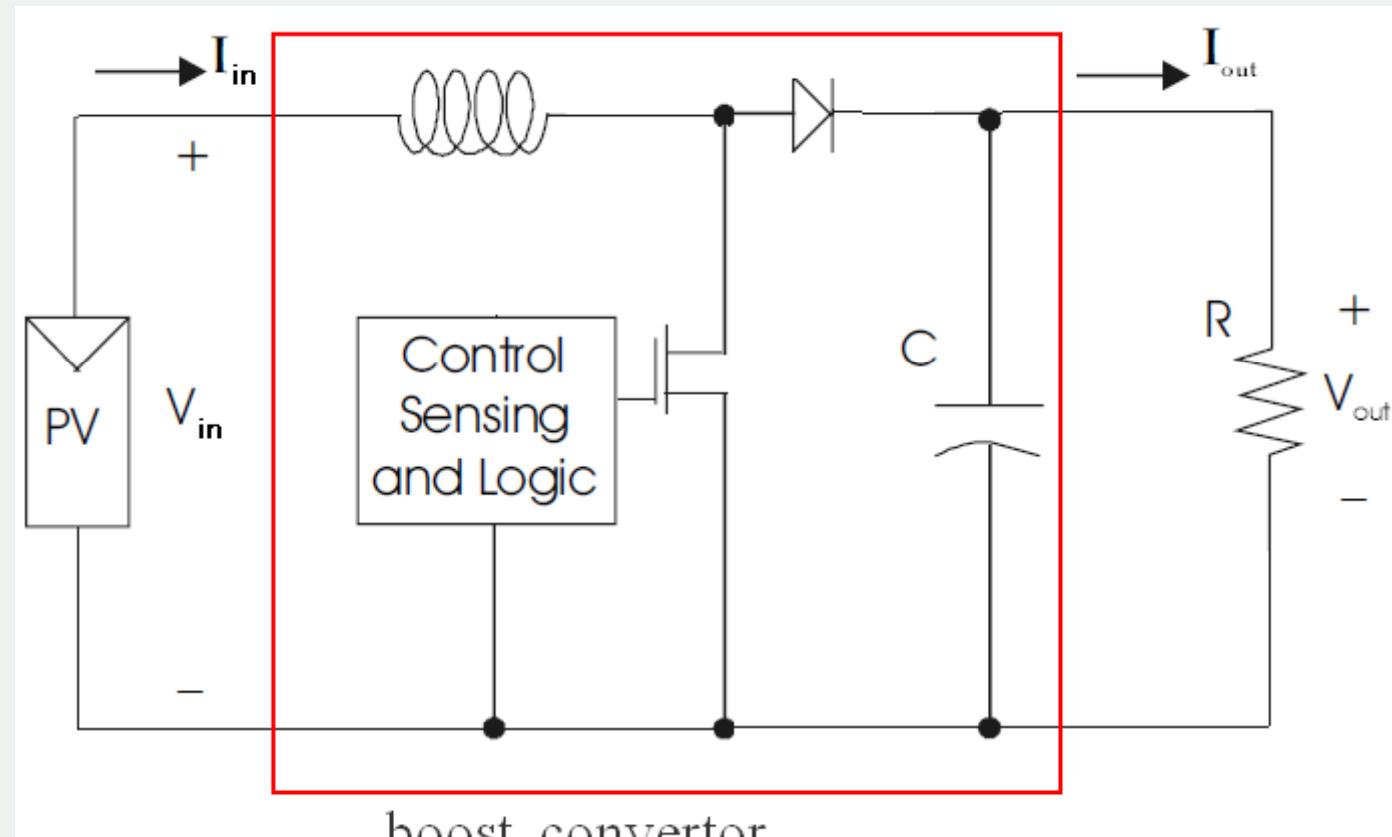


$$V_{out} = DV_{in}, \quad I_{out} = I_{in} / D, \text{ where } D \text{ is duty cycle of MOSFET}$$

MPPT circuits

2
0
1
2

A boost convertor

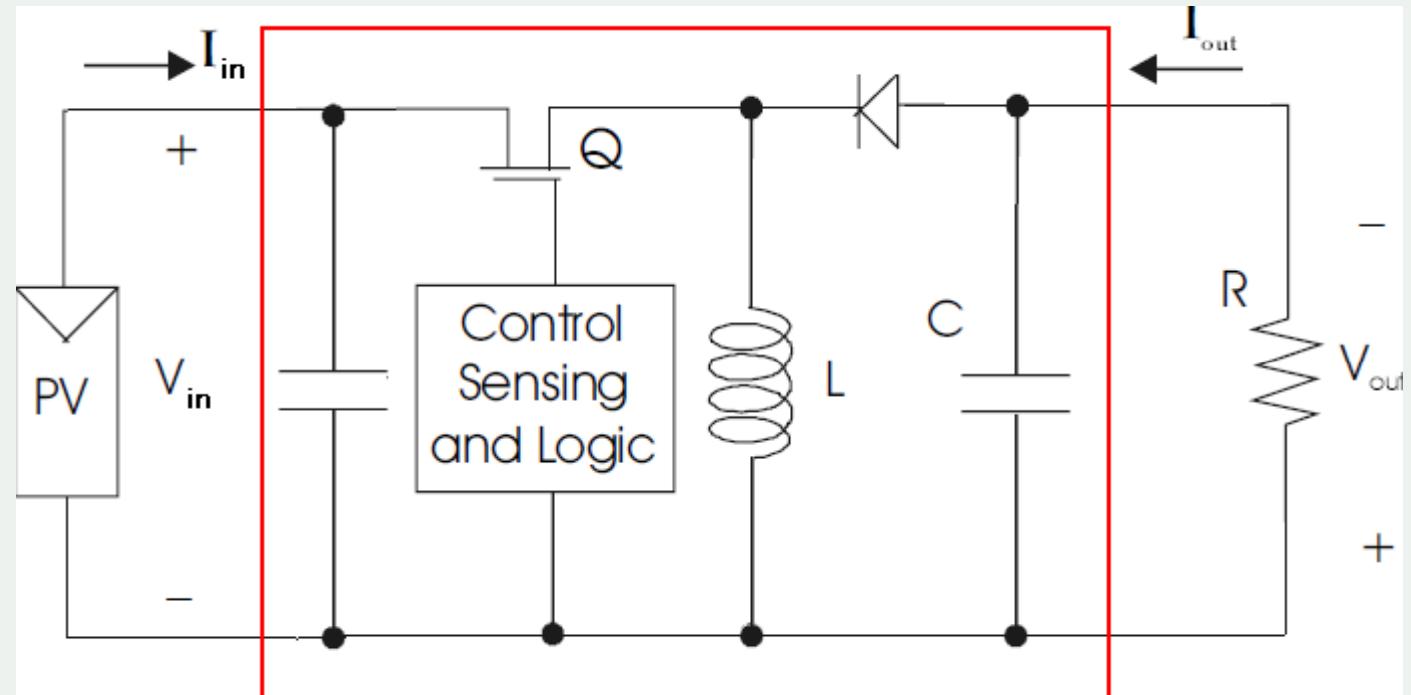


$$V_{out} = \frac{1}{1-D} V_{in}, I_{out} = (1-D) I_{in}, \text{ where } D \text{ is duty cycle of MOSFET}$$

MPPT circuits

2
0
1
2

A buck-boost convertor



buck-boost convertor

$$V_{out} = \frac{D}{1-D} V_{in}, \quad I_{out} = \frac{(1-D)}{D} I_{in}, \text{ where } D \text{ is duty cycle of MOSFET}$$

Inverters

2
0
1
2



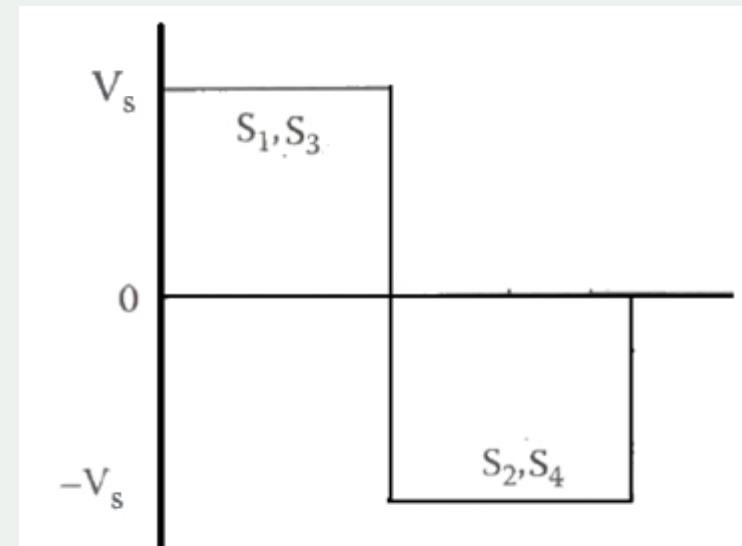
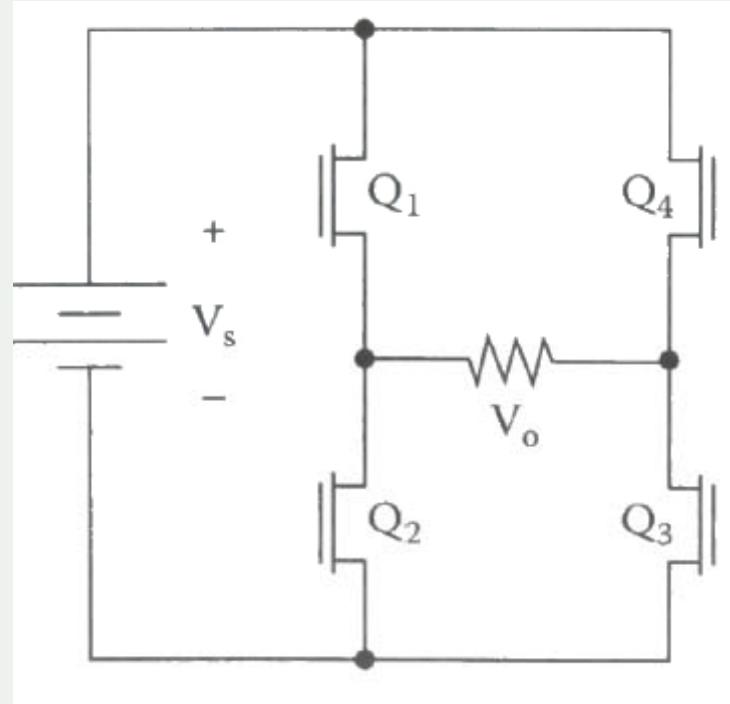
Different type
Of Inverters

- Square Wave Inverters
- Modified Sine Wave Inverters
- Pulse Width Modulated Inverters

Square Wave Inverters

2
0
1
2

Conventional Inverter (Square wave inverters)

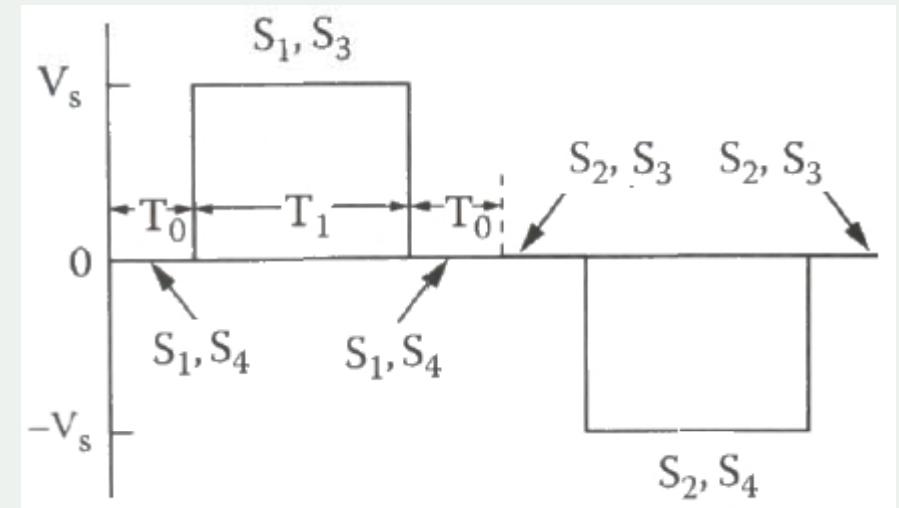
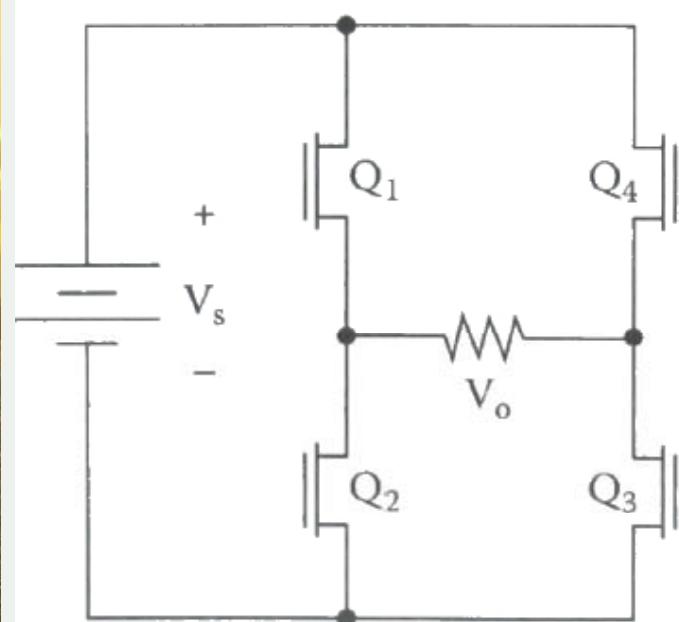


Harmonics?



Modified Square Wave Inverters

Modified square wave inverters

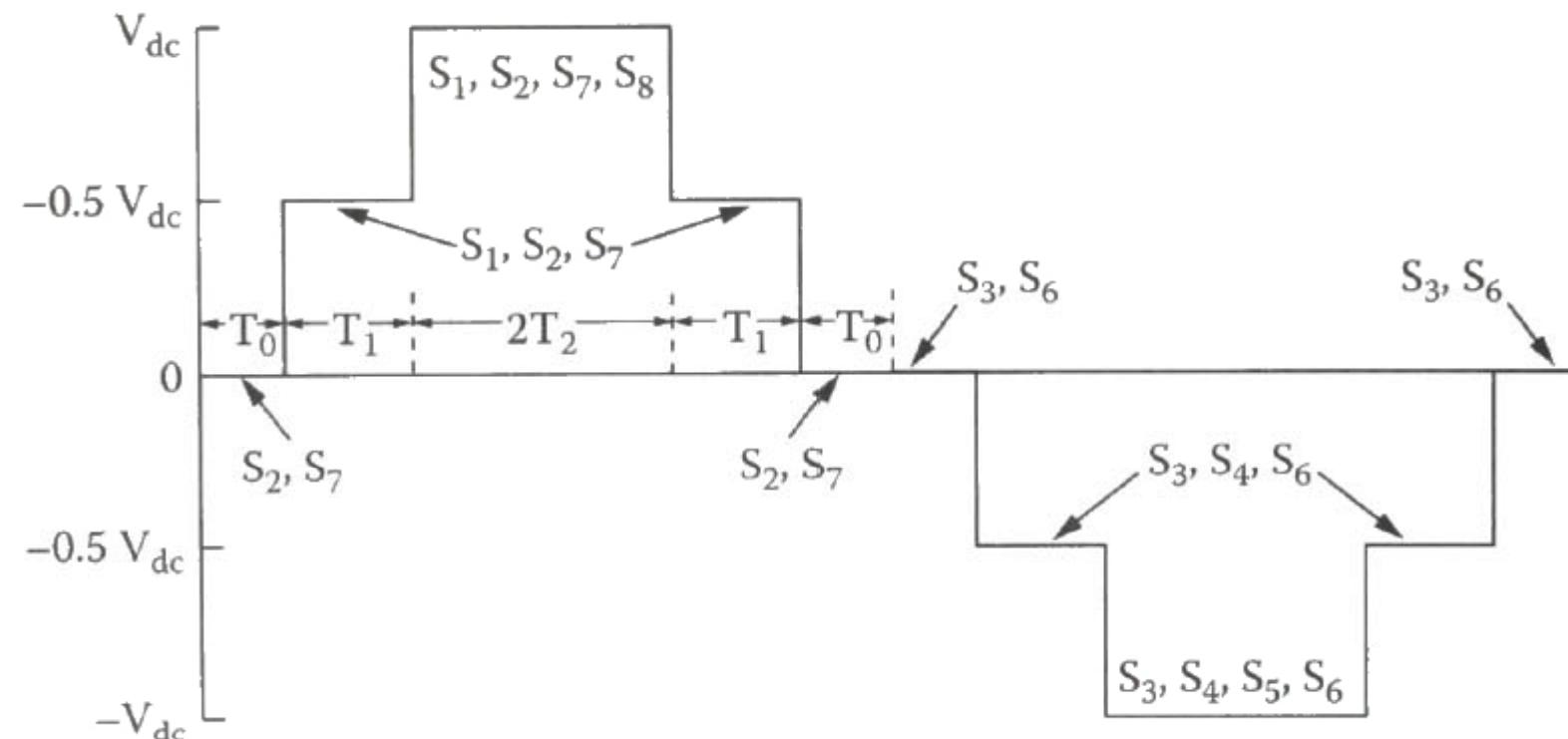


Harmonics?



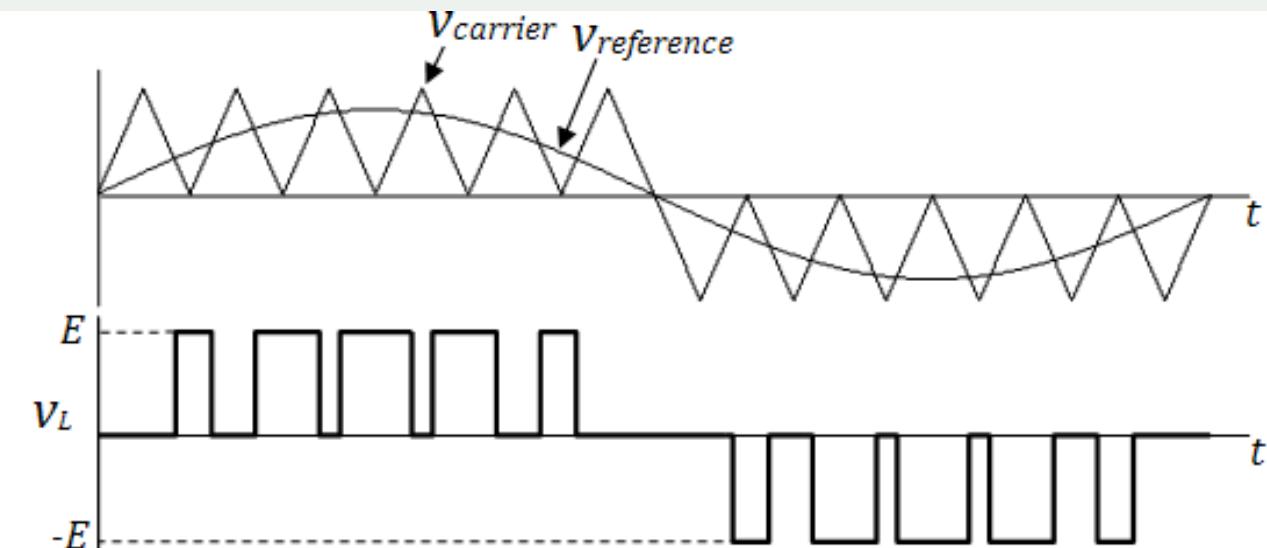
Modified Square Wave Inverters

Multi Level Converters



Harmonics?

PWM Inverters

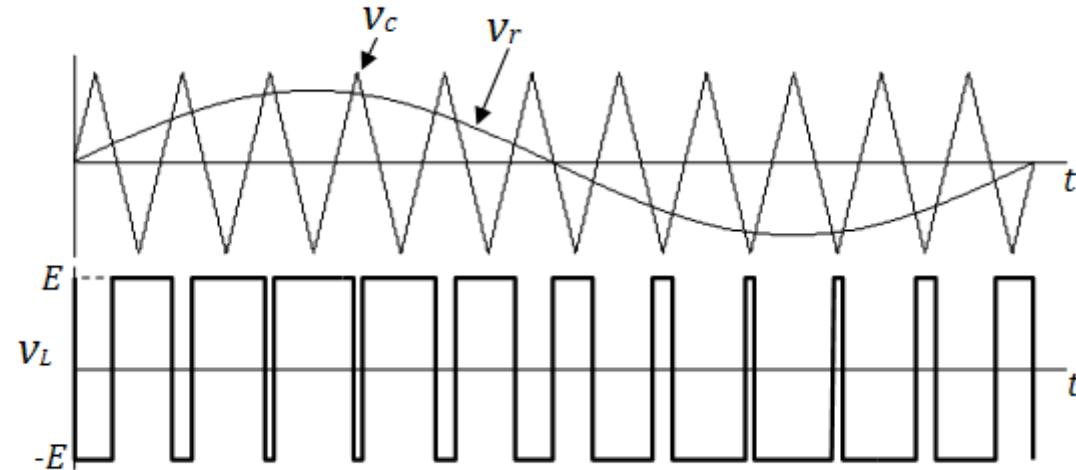
2
0
1
2Unipolar SPWM, $m_a = 0.8$:

PWM Inverters

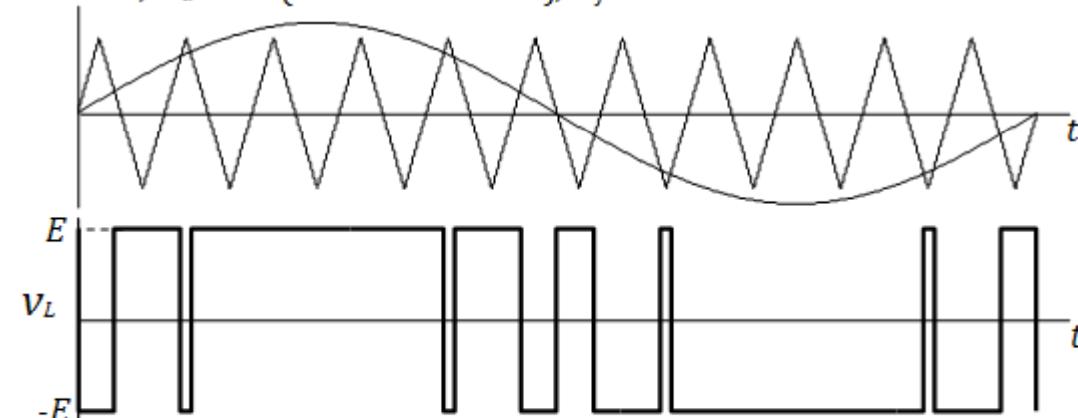
2
0
1
2

Basis of PWM is shifting harmonic frequency and filtering them.

Bipolar SPWM, $m_a = 0.8$ (linear), $m_f = 11$:



Bipolar SPWM, $m_a = 1.2$ (overmodulation), $m_f = 11$:

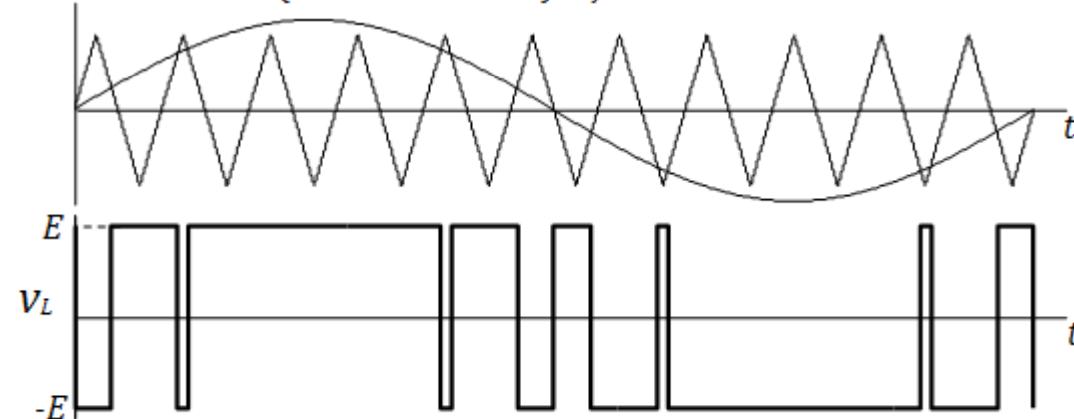


33

PWM Inverters

2
0
1
2

Basis of PWM is shifting harmonic frequency and filtering them.

Bipolar SPWM, $m_a = 1.2$ (overmodulation), $m_f = 11$:

PWM Inverters

2
0
1
2